WEST Search History

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DATE: Thursday, August 04, 2005

Hide?	<u>Set</u> Name	Query	<u>Hit</u> Count		
	DB=EPAB,JPAB,DWPI; PLUR=YES; OP=ADJ				
	L47	(control loop) near3 covariance	0		
I	L46	L44 and I43	0		
I	L45	L44 and I43	0		
m	L44	dynamic states!	55		
	L43	L42 and I38	61		
	L42	integrated control	1970		
M	L41	estimat\$5 near3 (oversteer\$3 or understeer\$3)	5		
	L40	(control loop) same (dynamic state)	0		
	L39	estimat\$5 steering behavior	0		
	L38	vehicle same steering	55451		
	DB=PGPB; PLUR=YES; OP=ADJ				
	L37	L35 same I27	4		
	L36	L35 same I28	0		
m	L35	dynamic states!	85		
	L34	estimat\$5 near3 (oversteer\$3 or understeer\$3)	5		
	L33	(control loop) near3 covariance	0		
m	L32	L31 and I28	10		
	L31	integrated control	1750		
	L30	(control loop) same (dynamic state)	5		
	L29	estimat\$5 steering behavior	0		
	L28	(oversteer\$3 or understeer\$3) same L27	171		
	L27	vehicle same steering	9689		

DB=USPT; PLUR=YES; OP=ADJ					
	L26	(control loop) near3 covariance	0		
	L25	L24 not (L10 or L13 or L15 or L17 or L18 or L19 or I21)	29		
	L24	L22 same I7	34		
	L23	L22 and I7	129		
	L22	yaw near2 control\$4	2175		
E	L21	L20 not (L10 or L13 or L15 or L17 or L18 or L19)	40		
	、L20	L16 and L5	49		
	L19	L9 not (L10 or L13 or L15 or L17 or L18)	18		
	L18	(control loop) same (dynamic state)	5		
	L17	vehicle same stability same L16	12		
	L16	integrated control	3601		
	L15	estimat\$5 near3 (oversteer\$3 or understeer\$3)	5		
	L14	estimat\$5 steering behavior	0		
	L13	L12 not L10	29		
	L12	('6035251')[URPN]	32		
	L11	6035251.pn.	1		
	L10	L9 and L5	19		
	L9	L8 and L7	39		
	L8	integrat\$3 near3 control\$4	47625		
	L7	(oversteer\$3 or understeer\$3) same L6	592		
	L ₆	vehicle same steering	34043		
	L5	L1 or L2 or L3 or L4	3001		
	L4	(180/443).ccls.	404		
	L3	(303/146).ccls.	283		
	L2	(280/5.503 280/5.51).ccls.	236		
m	L1	(701/41 701/42 701/37 701/70 701/48).ccls.	2371		

END OF SEARCH HISTORY